# Bio Jechnology 

# The study based on four-dimensional matrix DCT distance education video compression technology 

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## ABSTRACT

In the gorgeous era, the role of video in the human life growing. However, the highdefinition picture quality caused the difficulty in storage. In order to save more resources and maintain the quality of image, this article found out the method to solve the problem of remote compression through combining the four-dimensional matrix discrete cosine transform with statistical quantification firstly, then validated its effect in practical application according to the specific examples. The results shows that the compression through combining the integer transform with quantization achieved the desired effect.

## KEYWORDS

Discrete cosine transform; Four-dimensional matrix; Discrete integer transform; Video compression; Distance education.

## INTRODUCTION

Nowadays, in the advanced information era, Video is particularly important in human life., the video is essential whether concerning about national affairs or relax in their leisure time. However, the video production process is known by very few people, because it is a very complicated process. The entire process including the signal capture, recording and processing followed by storage, transmission and finally to reproduce the images for everyone to see. Today's video is no longer the past era of 'black and white'. With the rapid advancement of technology, the recording and the handle ability of video also continue to strengthen. Therefore, the resolution of the video is also at an alarming rate, also increased the amount of information stored, which led to the demand for video storage space is also growing. But the computer's storage space is limited, and the video which is too big in the video transmission is also very troublesome. So the compression of video become an inevitable trend. Video compression technology is also very important. Today there are many compression software, but most of the principles are the same. Today the most widely used method of compressed video technology is discrete cosine law. This article will analyze and study for four-dimensional matrix discrete cosine change of distance education video compression technology.

## ESTABLISHMENT AND SOLUTION OF THE MODEL

## The concept of four-dimensional discrete cosine transform matrix

Similar to the discrete Fourier transform, we could see the shadow of the Fourier transform from the discrete cosine transform. But its difference from Fourier transform is that discrete cosine transform is only applicable to real numbers, and its length is only half of a discrete Fourier transform. The commonly used discrete cosine transform can be divided into two categories. I.e., Inverse discrete cosine transform and inverse discrete cosine transform. And an inverse discrete cosine transform is often used in video compression or encoding process.

## The definition of four-dimensional discrete cosine transform matrix

Now define a four-dimensional matrix A, is a data matrix $I \times J \times K \times L$, formula is as follows:

$$
A_{I \times J \times K \times L}=\left[a_{i j k l}\right]_{I \times J \times K \times L}
$$

Among them, $a_{i j k l}$ is an element for the matrix $A_{I \times J \times K \times L}$. For the solution of four-dimensional discrete cosine transform, now set
$\left[C_{\text {wws }}\right] L=\left\{\begin{array}{c}\sqrt{\frac{2}{N} \cos \frac{i \pi(2 i+1)}{2 N}}, i \neq 0 \\ \frac{1}{\sqrt{N}}, i=0\end{array}\right.$
When $L=1, i=u, j=v$;
When $L=2, i=u, j=w$;
when $L=3, i=u, j=s$;
when $L=4, i=v, j=w$;
when $L=5, i=v, j=s$
when $L=6, i=w, j=s$;
If $A$ and $S$ are four-dimensional matrix, then the discrete cosine transform of $S$ is:

$$
\begin{aligned}
& S=\left(C_{6}\left(C_{1} A C_{1}^{T 1}\right) C_{6}^{T V 1}\right)_{V I} \\
& =\left(C_{1}\left(C_{6} A C_{6}^{T V 1}\right)_{V I} C_{1}^{\mathrm{M}}\right) \\
& =\left(C_{5}\left(C_{2} A C_{2}^{\text {TII }}\right)_{I I} C_{5}^{T V}\right)_{V} \\
& =\left(C_{2}\left(C_{5} A C_{2}^{T V}\right)_{V} C_{2}^{T I I}\right)_{\|} \\
& =\left(C_{3}\left(C_{4} A C_{4}^{T V}\right)_{\text {VV }} C_{3}^{T \text { III }}\right)_{\text {III }} \\
& =\left(C_{4}\left(C_{3} A C_{3}^{T I I I}\right)_{\text {II }} C_{4}^{\text {TVV }}\right)_{\mathrm{IV}}
\end{aligned}
$$

then the discrete cosine transform of $A$ is:

$$
\begin{aligned}
A & =\left(C_{6}^{T \mathrm{VII}}\left(C_{1}^{\mathrm{I}} B C_{1}\right) C_{6}\right)_{\mathrm{VI}} \\
& =\left(C_{1}^{\mathrm{II}}\left(C_{6}^{T \mathrm{VI}} B C_{6}\right)_{\mathrm{VI}} C_{1}\right) \\
& =\left(C_{5}^{\mathrm{TV}}\left(C_{2}^{\text {TII }} B C_{2}\right)_{\| I} C_{5}\right)_{\mathrm{V}} \\
& =\left(C_{2}^{\text {TII }}\left(C_{2}^{T V} A C_{5}\right)_{\mathrm{V}} C_{2}\right)_{\| I} \\
& =\left(C_{3}^{T \mathrm{III}}\left(C_{4}^{T \mathrm{VV}} A C_{4}\right)_{\mathrm{VV}} C_{3}\right)_{\mathrm{II}} \\
& =\left(C_{4}^{\text {TVV }}\left(C_{3}^{\text {IIII }} A C_{3}\right)_{\mathrm{III}} C_{4}\right)_{\mathrm{VV}}
\end{aligned}
$$

The matrix $A$ and the digital in matrix represent the difference of the type that they transpose.
In the encoding and compression processing of a color video, each pixel of the video can be converted into one of the elements in four-dimensional matrix. Therefore, the pixel values of the video can be expressed as $f(x, y, z, t)$, Where $x, y, ~ z$ are three-dimensional coordinate components, I.e., horizontal, vertical, and the vertical component, trepresents the time. Therefore, the video formula can be written as:
$\{f(x, y, z, t) x=0,1, \ldots, M-1 ; Y=0,1, \ldots, N-1 ; Z=0,1, \ldots, L-1 ; T=0,1, \ldots, H-1\}$
It is represented as a discrete linear transformation equation, as the following equation:
$F(u, v, w, s)=\sum_{x=0}^{M-1} \sum_{y=0}^{N-1} \sum_{z=0}^{L-1} \sum_{t=0}^{H-1} f(x, y, z, t) p(u, v, w, s, x, y, z, t)$
In the above formula $F(u, v, w, s)$ is called a transform coefficient of $f(x, y, z, t)$, and the transform nuclear is as follows:
$p(u, v, w, s, x, y, z, t)$,
$u=0,1, \ldots, M-1 ; v=0,1, \ldots, N-1 ; w=0,1, \ldots, L-1 ; s=0,1, \ldots, H-1$
Similarly, the inverse transform of the matrix can be expressed as:
$F(x, y, z, t)=\sum_{u=0}^{M-1} \sum_{v=0}^{N-1} \sum_{w=0}^{L-1} \sum_{s=0}^{H-1} F(u, v, w, s) q(u, v, w, s, x, y, z, t)$
Then:

$$
\begin{aligned}
& q(u, v, w, s, x, y, z, t) \\
& x=0,1, \ldots, M-1 ; y=0,1, \ldots, N-1 ; z=0,1, \ldots, L-1 ; t=0,1, \ldots, H-1
\end{aligned}
$$

is the inverse transform core.
Now regard $f(x, y, z, t)$ as a element of four-dimensional matrix, and treat it as a special case of linear transformation, it's discrete cosine transform can be expressed as:
$F(u, v, w, s)=\overline{\frac{2^{4}}{M N L H}} c(u) c(v) c(w) c(s) \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} \sum_{z=0}^{L-1} \sum_{t=0}^{H-1}$
$f(x, y, z, t) \cos \left[\frac{(2 x+1) \pi u}{2 M}\right] \cos \left[\frac{(2 y+1) \pi v}{2 N}\right] \cos \left[\frac{(2 z+1) \pi w}{2 L}\right] \cos \left[\frac{(2 t+1) \pi s}{2 H}\right]$
Among them, $u=0,1, \ldots, M-1 ; v=0,1, \ldots, N-1 ; w=0,1, \ldots, L-1 ; s=0,1, \ldots, H-1$ 。
Its inverse discrete cosine transform can be represented as:

$$
\begin{aligned}
f(x, y, z, t)= & =\frac{2^{4}}{M N L H} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} \sum_{z=0}^{L-1} \sum_{t=0}^{H-1} F(u, v, w, s) c(u) . \\
& c(v) c(w) c(s) \cos \left[\frac{(2 x+1) \pi u}{2 M}\right] \cos \left[\frac{(2 y+1) \pi v}{2 N}\right] \cos \left[\frac{(2 z+1) \pi w}{2 L}\right] \cos \left[\frac{(2 t+1) \pi s}{2 H}\right]
\end{aligned}
$$

Among them, $x=0,1, \ldots, M-1 ; y=0,1, \ldots, N-1 ; z=0,1, \ldots, L-1 ; t=0,1, \ldots, H-1$,
$c(u)=\left\{\begin{array}{l}\frac{1}{\sqrt{2}}, u=0 \\ 1, \text { others }\end{array} ; c(v)=\left\{\begin{array}{l}\frac{1}{\sqrt{2}}, v=0 \\ 1, \quad \text { others }\end{array} ;\right.\right.$
$c(w)=\left\{\begin{array}{l}\frac{1}{\sqrt{2}}, w=0 \\ 1, \text { others }\end{array} ; c(s)=\left\{\begin{array}{l}\frac{1}{\sqrt{2}}, s=0 \\ 1, \text { others }\end{array}\right.\right.$ 。
The realization of the four dimensional discrete cosine transform for Video compression
In this article, the video is divided into multiple child on $R, G, B$ component and time $t$ according to four-dimensional matrix model, then transform and coding the four dimensional discrete cosine. See Figure 1for specific process.


Figure 1 : Four-dimensional discrete cosine transform video encoding process
Take the transform of a as an example, when $x \in Z$, if $a, b \in Z$, then can be introduced $y \in Z$. when $b \in Z, a= \pm 1$ or $\pm i$, can get the conclusion that $y=a x+b$ is completely reversible. then the factors a and b are integers. when $b \notin Z$, by integer to ensure that the results of a computation as an integer. At the same time also ensure $y=a x+b$ transformation reversible. A transformation matrix is described below:

$$
\left[\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{n}
\end{array}\right]=\left[\begin{array}{cccc}
1 & a_{12} & \ldots & a_{1 n} \\
0 & 1 & \ldots & \vdots \\
\vdots & 0 & \ddots & a_{\ldots n} \\
0 & \ldots & 0 & 1
\end{array}\right] \times\left[\begin{array}{c}
x_{1} \\
x_{2} \\
\vdots \\
x_{n}
\end{array}\right]
$$

Set $A$ in the above formula as the basic matrix, then can get:
$y_{i}=x_{i}+\left|\sum_{n=j+1}^{N} a_{j n} x_{n}\right|, j=1,2, \ldots, N$
It's inverse transformation expressed as :
$x_{j}=y_{j}-\left|\sum_{n=j+1}^{N} a_{j n} x_{n}\right|$
$j=N, N-1, \ldots, 1$
Thus, if $A$ can be decomposed into an upper triangular matrix, the transformation of $y=A x$ can be carried out inverse transform.

Now set $u=v=w=s=N$, if $w, s$ known, then the orthogonal transform nuclear can be regarded as a matrix of $N \times N$, then
$c_{i j}=\left[\begin{array}{cccc}\frac{1}{\sqrt{N}} & \frac{1}{\sqrt{N}} & \cdots & \frac{1}{\sqrt{N}} \\ \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{\pi}{2 N} & \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{3 \pi}{2 N} & \cdots & \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{(2 n-1) \pi}{2 N} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{(N-1) \pi}{2 N} & \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{3(N-1) \pi}{2 N} & \cdots & \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{(N-1)(2 N-1) \pi}{2 N}\end{array}\right]$
The $C_{6}$ above is in contrast, by the nature of the 4 d - MDCT, 4D-MDCT are orthogonal transformation, Therefore, when a determinant of $A$ is $|A|= \pm 1$, can prove that a matrix can be decomposed into reversible triangular fundamental matrix, that is:
$A=P L U S_{0}$
Wherein $P$ represents a permutation matrix, upper and lower triangular matrix with $L$ and $U$ respectively, and $S_{0}$ can be expressed as:
$S_{0}=I+e_{n} s_{o}=I+e_{n}\left(s_{1}, s_{2}, \ldots, s_{n-1}, 0\right)$
$e_{n}$ indicates a vector in column $N$ of $S_{0}, s_{n}$ is a vector element in the zero column.
Each element of orthogonal transform nuclear can be carried out ina triangular decomposition by $P L U S_{0}$, then composit each of the elemental of 4D-MDCT into a nuclear matrix, So 4D-MDCT transform can be achieved.

In this paper, take the four dimensional discrete cosine transform for example, that $S=\left(C_{6}\left(C_{1} A C_{1}^{T 1}\right) C_{6}^{T V 1}\right)_{\mathrm{VI}}$ prove its overall nuclear matrix transformation. Seen from above, nuclear
transformation matrices $C_{1}, ~ C_{6}, ~ C_{1}^{T}$ and $C_{6}^{t}$ all belong orthogonal matrix, Therefore, they can be broken down into the triangle decomposition.
If $T_{i}$ is the nuclear transformation factorization of $C_{i}$, its expression is as follows:
$T_{i}=P_{i} L_{i} U_{i} S_{0 i}$
Then the four-dimensional discrete cosine integral transform expression is:


In the above formula, frist, second, third, fourth indicates the order abcd transformation. Similarly, the opposite order of the inverse transformation. can be reverse with the procedure above.

## Experimental validation of the four-dimensional discrete cosine transform matrix

Now make a four dimensional discrete cosine transform on an image of a color video which sequence is Miss America and Suzie, and compress it. The processing sequence is as follows:
Firstly, divide the sequence $R G B$ into a four-dimensional matrix of $3 \times 3 \times 3 \times 3$, and make a four dimensional discrete cosine transform on it, then obtain the four-dimensional matrix transformation. Secondly, encode the quantified using statistical methods to the resultant transformation matrix, then take the code number in integer values. Thirdly, compare the results with the floating-point matrix obtained by dimensional discrete cosine transform. The evaluation standard of image is PSNR, the expression is as follows:
$P S N R=10 \log \frac{255 \times 255}{M S E} d B$
The comparative results as shown in TABLE 1.
The TABLE 1 above indicates that when ratios of two image is108,92.6,81 in the original image data is image data and the modification data of each frame. Figure 2 and Figure 3 are the comparison chart of two images.


Figure 2 : The original image and contrast figure after repair of Miss America


Figure 3 : comparison chart of Suzie before and after change

TABLE 1 : The comparison on 4D-MDCT of integer and floating-point

| Video sequences | CR | Frame | floating-point 4D-MDCT |  |  |  | integer 4D-MDCT |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | PSNR (R) | PSNR (G) | PSNR (B) | $\overline{\text { PSNR }}$ | PSNR (R) | PSNR (G) | PSNR (B) | $\overline{\text { PSNR }}$ |
| MISS America | 108 | 12 | 29.616 | 32.945 | 31.337 | 31.332 | 31.530 | 33.818 | 32.450 | 32.600 |
|  |  | 13 | 29.656 | 33.084 | 31.345 | 31.365 | 31.530 | 33.818 | 32.450 | 32.600 |
|  |  | 14 | 29.601 | 33.093 | 31.345 | 31.530 | 31.530 | 33.818 | 32.450 | 32.600 |
|  | 92.6 | 12 | 31.201 | 34.258 | 34.354 | 32.411 | 32.567 | 33.588 | 33.710 | 34.110 |
|  |  | 13 | 31.195 | 34.467 | 32.598 | 32.754 | 32.948 | 35.830 | 33.710 | 34.144 |
|  |  | 14 | 31.031 | 34.488 | 32.300 | 32.600 | 32.948 | 35.830 | 33.710 | 34.144 |
|  | 81 | 12 | 32.885 | 36.358 | 33.915 | 34.384 | 35.122 | 37.716 | 35.344 | 36.061 |
|  |  | 13 | 32.968 | 36.445 | 33.929 | 34.456 | 35.122 | 37.716 | 35.344 | 36.061 |
|  |  | 14 | 32.654 | 36.480 | 33.625 | 34.248 | 35.122 | 37.716 | 35.344 | 36.061 |
| Suzie | 108 | 12 | 28.983 | 30.262 | 29.434 | 29.561 | 30.806 | 31.411 | 31.142 | 31.118 |
|  |  | 13 | 29.287 | 30.585 | 29.775 | 29.881 | 30.970 | 31.600 | 31.319 | 31.297 |
|  |  | 14 | 28.804 | 29.944 | 29.364 | 29.365 | 30.651 | 31.227 | 31.053 | 30.976 |
|  | 92.6 | 12 | 30.192 | 31.594 | 30.639 | 30.809 | 32.111 | 32.817 | 32.569 | 32.499 |
|  |  | 13 | 30.730 | 32.011 | 31.127 | 31.290 | 32.334 | 33.218 | 32.817 | 32.790 |
|  |  | 14 | 30.253 | 31.281 | 30.643 | 30.720 | 32.108 | 32.688 | 32.566 | 32.454 |
|  | 81 | 12 | 31.722 | 33.056 | 31.942 | 32.248 | 33.818 | 34.515 | 34.152 | 34.162 |
|  |  | 13 | 32.181 | 33.449 | 32.365 | 32.663 | 34.152 | 34.910 | 34.515 | 34.526 |
|  |  | 14 | 31.618 | 32.666 | 31.828 | 32.035 | 33.815 | 34.327 | 34.149 | 34.097 |

## CONCLUSION

This article found out the method to solve the problem of remote compression through combining the four-dimensional matrix discrete cosine transform with statistical quantification firstly, then validated its effect in practical application according to the specific examples. The results shows that the compression through combining the integer transform with quantization achieved the desired effect.

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