



BioTechnology

An Indian Journal

FULL PAPER

BTAIJ, 8(5), 2013 [659-663]

Application of monte carlo method in numerical integral equations

Junfeng Lai, Zaizai Yan*, Jingyu Wang

College of Science, InnerMongolia University of Technology, Hohhot, 010051 (CHINA)

ABSTRACT

In this paper, we review the history of Monte Carlo methods. Then we study a numerical method based on Monte Carlo methods for the solution of integral equations. We give some numerical results. The results are supported by an application with Monte Carlo methods. Some concluding remarks are given according to the numerical results.

© 2013 Trade Science Inc. - INDIA

KEYWORDS

Monte carlo methods;
Markov chain;
Integral equation;
Numerical experiments.

INTRODUCTION

During World war II, several famous physicists and mathematicians studied Monte Carlo methods such as J. von Neumann, S. Ulam, and E. Fermi. They worked for the United States Manhattan project^[1]. In 1948, N. Metropolis on the ENIAC first carried out actual Monte Carlo methods. In 1949 N. Metropolis and S. Ulam published first paper on Monte Carlo methods. Monte Carlo methods had greatest influence on the science and engineering. Monte Carlo (MC) methods are stochastic techniques meaning. They are based on the use of random numbers and probability statistics to investigate problems. You can find MC methods used in everything from economics to nuclear physics to regulating the flow of traffic. Of course the way they are applied varies widely from field to field, and there are dozens of subsets of MC even within chemistry. But, strictly speaking, to call something a "Monte Carlo" experiment, all you need to do is use random numbers to examine some problem.

In 1950 Markovian chain, S. Forsythe and R. Leibler^[5] find the inverse of a matrix by using Monte

Carlo methods. Since then, many numerical algorithms based on Monte Carlo methods have been applied and varies widely from field to field.

In this paper, we mainly study the Monte Carlo methods in solving integral equations. Our idea for solving integral by Monte Carlo method is using Markov chain with State space. In section 2 we review briefly the Monte Carlo methods. In section 3 and section 4 we use Monte Carlo methods to evaluate integrals. We give numerical experiments and a summary remarks in section 6.

MONTE CARLO METHODS

Assume that X_1, \dots, X_n are i.i.d. $f(x|\theta)$, $x \in \mathcal{X}$, with $E(g(X_i)) = \lambda_i$, for all $i = 1, 2, \dots, n$. Then the Strong Law of Large Numbers (S.L.L.N) tells as with probability 1 we have

$$\frac{1}{n} \sum_{i=1}^n g(x_i) \rightarrow \lambda, \text{ as } n \rightarrow \infty.$$

The SLLN states that if we were to generate a

FULL PAPER

large number of values from $f(x|\theta)$, then in order to approximate $\lambda = E(g(X))$, all we have to do is take average of the generated values evaluated through $g(x)$.

The value $g(x_1), \dots, g(x_n)$ can be thought of as realizations from the random variable.

The Monte Carlo approach consists of using this idea to evaluate the integral $E(g(X)) = \lambda$

$$\lambda = E(g(X)) = \int_{\mathcal{X}} g(x) f(x) dx \approx \frac{1}{n} \sum_{i=1}^n g(X_i),$$

where X_1, \dots, X_n a random sample from $f(x|\theta)$.

USING MONTE CARLO METHODS TO EVALUATE INTEGRALS

Suppose we want to evaluate the integral $\int_{\mathcal{X}} h(x) dx$, where $h(x)$ doesn't have to be a p.d.f., and \mathcal{X} could be the whole real line. Depending on the form of \mathcal{X} , we have different ways of attacking the problem. First we present transformation to the interval and then a general method without transforming.

Evaluating an integral over $\mathcal{X} = [0, 1]$

To evaluate $\int_0^1 h(x) dx$ we write

$$\int_0^1 h(x) dx = \int_0^1 h(x) I(0 \leq x \leq 1) dx,$$

And hence the algorithm becomes:

Step 1: Generate $U_1, \dots, U_L, i, d.U(0, 1)$ for a very large L .

Step 2: Calculate $\int_0^1 h(x) dx \approx \frac{1}{L} \sum_{i=1}^L h(U_i)$.

Evaluating an integral over $\mathcal{X} = [a, b]$

To evaluate $\int_a^b h(x) dx$ we take the transformation

$$y = \frac{x-a}{b-a} \Rightarrow x = (b-a)y + a, dx = (b-a)dy$$

to obtain $\int_a^b h(x) dx = \int_0^1 (b-a)h((b-a)y + a) dy$, and

hence we can use the algorithm in section 3.

Evaluating an integral over $\mathcal{X} = [a, +\infty)$

To evaluate $\int_a^{+\infty} h(x) dx$, we take the transformation

$$y = \frac{1}{x-a+1} \Rightarrow x = \frac{1}{y} + a - 1, dx = -\frac{1}{y^2} dy,$$

To obtain

$$\int_a^{+\infty} h(x) dx = \int_0^1 \frac{1}{y^2} h\left(\frac{1}{y} + a - 1\right) dy,$$

and hence we can use the algorithm in section 3.1.

Evaluating an integral over $\mathcal{X} = [-\infty, b]$

To evaluate $\int_{-\infty}^b h(x) dx$, we take transformation

$$y = \frac{1}{b-x+1} \Rightarrow x = -\frac{1}{y} + b + 1, dx = \frac{1}{y^2} dy,$$

To obtain

$$\int_{-\infty}^b h(x) dx = \int_0^1 \frac{1}{y^2} h\left(-\frac{1}{y} + b + 1\right) dy,$$

and hence we can use the algorithm in section 3.1.

Evaluating an integral over $\mathcal{X} = [-\infty, +\infty)$

To evaluate $\int_{-\infty}^{+\infty} h(x) dx$ we write it as

$$\int_{-\infty}^{+\infty} h(x) dx = \int_{-\infty}^0 h(x) dx + \int_0^{+\infty} h(x) dx,$$

and we fall in the previous cases. For the first integral

$\int_{-\infty}^0 h(x) dx$, we take the transformation

$$y = \frac{1}{1-x} \Rightarrow x = -\frac{1}{y} + 1, dx = \frac{1}{y^2} dy,$$

and for the second $\int_0^{+\infty} h(x) dx$, the transformation

$$y = \frac{1}{x+1} \Rightarrow x = \frac{1}{y} - 1, dx = -\frac{1}{y^2} dy,$$

and thus obtain $\int_{-\infty}^{+\infty} h(x) dx = \int_0^1 \frac{1}{y^2} h\left(-\frac{1}{y} + 1\right) dy + \int_0^1 \frac{1}{y^2} h\left(\frac{1}{y} - 1\right) dy = \int_0^1 \frac{1}{y^2} [h\left(-\frac{1}{y} + 1\right) + h\left(\frac{1}{y} - 1\right)] dy$

and hence we can use the algorithm in section 3.1 on those integrals.

MULTIVARIATE EXTENSIONS:USING TRANSFORMATIONS TO [0,1]

To evaluate the integral $\int_{\mathcal{X}} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p$, where the set is separable, i.e., we simply write

$$\int_{\mathcal{X}} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p = \int_{x_1} \dots \int_{x_p} h(x_1, x_2, \dots, x_p) dx_1 \dots dx_p$$

and then take appropriate transformation depending on form of the \mathcal{X}_i 's. For instant if $\mathcal{X} = \mathcal{X}_1 \times \mathcal{X}_2 = \mathbb{R}^2$, then we would write

$$\begin{aligned} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 + \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 \\ &= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 + \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 \\ &+ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 + \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(x_1, x_2) dx_1 dx_2 \\ &= \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} h\left(-\frac{1}{y_1} + I, -\frac{1}{y_2} + I\right) dy_1 dy_2 + \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} h\left(-\frac{1}{y_1} + I, \frac{1}{y_2} - I\right) dy_1 dy_2 \\ &+ \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} h\left(\frac{1}{y_1} - I, -\frac{1}{y_2} + I\right) dy_1 dy_2 + \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} h\left(\frac{1}{y_1} - I, \frac{1}{y_2} - I\right) dy_1 dy_2 \\ &= \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} [h\left(-\frac{1}{y_1} + I, -\frac{1}{y_2} + I\right) + h\left(-\frac{1}{y_1} + I, \frac{1}{y_2} - I\right)] dy_1 dy_2 \\ &+ \int_0^1 \int_0^1 \frac{1}{y_1^2 y_2^2} [h\left(\frac{1}{y_1} - I, -\frac{1}{y_2} + I\right) + h\left(\frac{1}{y_1} - I, \frac{1}{y_2} - I\right)] dy_1 dy_2 \end{aligned}$$

Multivariate extensions:No transformations

Consider now the integral

$$\begin{aligned} \int_{\mathcal{X}} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p &= \int_{x_1} \int_{x_2} \dots \int_{x_p} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p \\ &= \int_{x_1} \int_{x_2} \dots \int_{x_p} \frac{h(x_1, x_2, \dots, x_p)}{f(x_1, x_2, \dots, x_p)} f(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p \end{aligned}$$

Where

$$g(x_1, x_2, \dots, x_p) = \frac{h(x_1, x_2, \dots, x_p)}{f(x_1, x_2, \dots, x_p)}$$

and $f(x_1, x_2, \dots, x_p)$ is a multivariate p.d.f. with support $\mathcal{X} = \mathcal{X}_1 \times \mathcal{X}_2 \times \dots \times \mathcal{X}_p$, that is known and can be used to given us a random sample of random vectors, namely

$$\begin{aligned} \mathcal{X}_1 &= (x_{11}, x_{12}, \dots, x_{1p}), \\ \mathcal{X}_2 &= (x_{21}, x_{22}, \dots, x_{2p}), \\ &\dots \\ \mathcal{X}_n &= (x_{n1}, x_{n2}, \dots, x_{np}). \end{aligned}$$

Then the integral is approximated by

$$\begin{aligned} &\int_{\mathcal{X}} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p \\ &\approx \frac{1}{n} \sum_{i=1}^n g(x_i) \\ &= \frac{1}{n} \sum_{i=1}^n \frac{h(x_1, x_2, \dots, x_p)}{f(x_1, x_2, \dots, x_p)} \end{aligned}$$

Now for the case where \mathcal{X} imposes relationships on the vector \mathcal{X} . Here

$$\mathcal{X} = \{x = (x_1, \dots, x_p) \in \mathbb{R}^p : x_i = q_i(x_1, x_2, \dots, x_p), i = 1, 2, \dots, p\}.$$

We can easily bring this into one of the previous forms by considering

$$\begin{aligned} &\int_{\mathcal{X}} h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p \\ &= \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} I(x \in \mathcal{X}) h(x_1, x_2, \dots, x_p) dx_1 dx_2 \dots dx_p \end{aligned}$$

where $I(\cdot)$ the indicator of the set

Numerical experiments

Example 1

Consider

$$I_y = \int_A x^2 dA = \int_{\frac{b}{2}}^b h x^2 dx = \frac{b^3 h}{12}$$

for which the exact solution is 0.1667 when $b=1, h=2$.

TABLE 1 : Inertial moment results and relative errors of Monte Carlo

<i>N</i>	<i>Results</i>	<i>relative errors</i>
10	0.1500	10.00
100	0.1630	2.220
1000	0.1645	1.320
10000	0.1651	0.960

We can easily see that

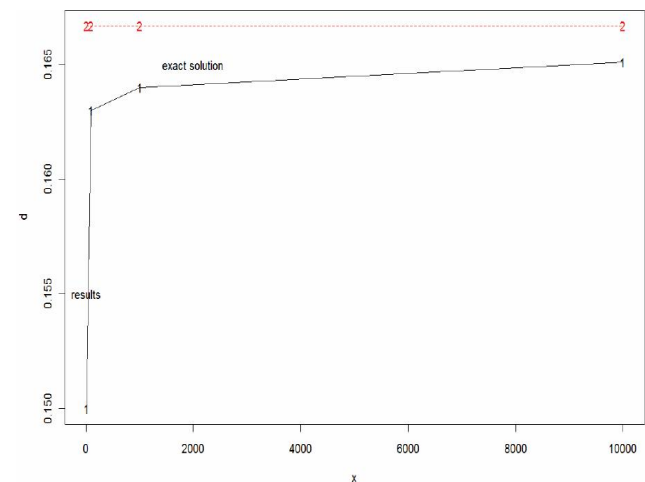


Figure 1 : Inertial moment results and relative errors of Monte Carlo

FULL PAPER

$$D(I_y) \approx \hat{D}(I_y) = \frac{I_y(I - I_y)}{N}$$

$$\sigma(I_y) \approx \hat{\sigma}(I_y) = \sqrt{\frac{I_y(I - I_y)}{N}}$$

TABLE 2 : Inertial moment results and variance of Monte Carlo

N	Results	variance
10	0.1500	0.00225
100	0.1630	0.00026569
1000	0.1645	0.0000270
10000	0.1651	0.000002725801

TABLE 3 : Inertial moment results and standard variance of Monte Carlo

N	Results	Standard variance
10	0.1500	0.047434
100	0.1630	0.0163
1000	0.1645	0.005196
10000	0.1651	0.001649

Example 2

Consider $\int_0^1 e^{-x} dx$ the exact solution is 0.6.

TABLE 4 : Inertial moment results and variance of Monte Carlo

Random r_1	Random r_2	$g(r_1) = e^{r_1-1}$	Number ($r_2 \leq g(r_1)$)				
0.266	0.914	0.742	0.791	0.480	0.918	0	1
0.606	0.925	0.751	0.295	0.674	0.928	0	1
0.454	0.417	0.936	0.121	0.579	0.558	0	1
0.698	0.252	0.480	0.781	0.730	0.473	1	0
0.037	0.916	0.863	0.115	0.382	0.919	0	1
0.846	0.001	0.576	0.847	0.857	0.368	1	0
0.915	0.532	0.496	0.732	0.919	0.626	1	0
0.107	0.255	0.493	0.174	0.409	0.475	0	1
0.548	0.011	0.196	0.121	0.636	0.372	1	1
0.489	0.835	0.495	0.155	0.600	0.848	1	1
sum				12.76			12
mean				0.638			0.60

CONCLUSION

The present study successfully applied a numerical algorithm with Monte Carlo method to solve integral equation. It can be seen that the proposed method is efficient and accurate to estimate the solution. Furthermore the results indicate that the present Monte Carlo

method is preferable when one needs to have a rough estimation.

ACKNOWLEDGEMENT

I shall extend my thanks to my supervisor Zaizai yan for help. This work was supported by National Natural Foundation of China (11161031) and Higher school science and technology research project of Inner Mongolia(NJ10085).

REFERENCES

- [1] N.Metropolism; The Beginning of the Monte Carlo MethodmLos Alamos Sxience, Special Issuem, 1-987.
- [2] S.Branford, C.Weihrauch, V.Alexandrov; A sparse parallel hybrid Monte Carlo algorithms for matrix computations, Proceedings of the 2005 International Conference on Computational Science, V.Sunderam et al, (Eds); Lecture Note in Computer Science, **3156**, 743-751 (2005).
- [3] F.M.Solaguren-Beascoa, J.M.Alegre-Colderon, P.M.Bravodiez; Implementation in Matlab of the ad-aptive Monte Carlo methods for the evaluation of measurement uncertainties[J].Accred Qual Assur, **14(2)**, 95-106 (2009).
- [4] I.Dimov, T.Dimov, T.Gurov; A new iterative Monte Carlo method for inverse matrix problem, J.Comput.Appl.Math., **92**, 15-35 (1998).
- [5] S.Forsythe, R.Leibler; Matrix inversion by a Monte Carlo method,Mathematical Table and Other Aids to Computation, **4**, 127-129 (1950).
- [6] J.Halton; Sequential Monte Carlo technique for the solution of linear systems, J.Sci.Comput., **9**, 231-257 (1994).
- [7] L.Kolotilina, A.Yeremin; Factorized sparse approximate inverse preconditionings I.Theorym SIAM J.Matrix Anal.Appl, **14**, 45-58 (1993).
- [8] Tasos C Christofides.A generalized randomized response technique.Metrika, **57**, 195-200 (2003).
- [9] V.Alexandrov, E.Atanassov, I.Dimov, S.Branford, A.Thandavan, C.Weihrauch; Parallel hybrid Monte Carlo algorithms for matrix computations, pre-printed, (2005).
- [10] N.Metropolis, S.Ulam; The Monte Carlo methods,J.Amer.Statist,Assoc, **44**, 335-341 (1994).
- [11] G.Stefanou, M.Papadrakakis; Assessment of spectral representation and Karhunen-Live exoansion

methods for the simulation of Gaussian stochastic fields, *Comput. Met. App. Mech. Eng.*, 2465-2477 (2007).

- [12] M. Fukushima; Restricted generalized Nash equilibria and controlled penalty algorithm. *Comput. Manag. Sci.*, **8**, 201-218 (2011).
- [13] Lin Huang, Jian Hou, Junfeng Lai; Approximation of interval Bezier surfaces, *Transaction of Nanjing University of Aeronautics & Astronautics*, Jun. 2011, **28(2)**, (2011).
- [14] Lin Huang, Junfeng Lai, Jian Hou; Trajectory-based Routing in Ad Hoc Network, *Journal of Computational Information Systems*, **6(10)**, 3209-3216 (2010).